## MISCELLANEA

## STATISTICAL CALCULATION OF THE VISCOSITY COEFFICIENTS OF THE ORDERED PHASES OF DNA MOLECULES

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Statistical calculation of the viscosity coefficients of the ordered phases of DNA molecules is performed. As a starting point of calculation, an expression which describes the tensor of viscous stresse is used, whereas calculations of time correlation functions that determine kinetic coefficients are performed with the aid of a relaxation equation which characterizes the evolution of the tensor order parameter.

Physically, the ordered phases revealed experimentally in the DNA molecule are interesting biological objects [1]. They represent concentrated solutions of the fragments of DNA molecules with the length close to their persistent length in ionic media formed by aqueous salt solutions. The latter possess a liquid-crystalline orientational order responsible for their anisotropy.

Orientational Order and Its Kinetics for the Ordered DNA Molecules. Since condensed states of the ensembles of DNA molecules have a liquid-crystalline orientational order, its description in both nematic and cholesteric liquid crystals should be made using an average value of the dynamic density of the tensor order parameter in the form of a spurless second-order tensor (see. e.g., [2]):

$$
\begin{equation*}
D_{i j}(\mathbf{x})=\frac{1}{2} \sum_{\mathrm{v}=1}^{N}\left(3 c_{i}^{v} c_{j}^{v}-\delta_{i j}\right) \delta\left(\mathbf{x}-\mathbf{x}^{v}\right) . \tag{1}
\end{equation*}
$$

The dynamic parameter of the density of the tensor order parameter is a nonconserved quantity, and therefore its evolution obeys the relaxation equation [2]:

$$
\begin{equation*}
\frac{d \delta \hat{D}_{i j}}{d t}=-\sum_{\alpha=1}^{3} \tau_{\alpha}^{-1} B_{i j k l}^{\alpha} \delta \hat{D}_{k l}, \tag{2}
\end{equation*}
$$

with $\hat{\delta} D_{i j}=\hat{D}_{i j}-D_{i j}^{0}$ representing the deviation of the tensor parameter from its equilibrium value $D_{i j}^{0}$.
The time correlation function of the tensor order parameter is determined in the form of integrals over the volume of the system with the aid of the relation

$$
\begin{equation*}
g_{i j k l}(t)=\frac{1}{V} \iint\left\langle\delta \hat{D}_{i j}(\mathbf{x}, t) \delta \hat{D}_{k l}\left(\mathbf{x}^{\prime}, 0\right)\right\rangle d \mathbf{x} d \mathbf{x}^{\prime}, \tag{3}
\end{equation*}
$$

in which the angular brackets denote equilibrium averaging. Since the equation of motion for the time correlation function $g_{i j k l}(t)$ coincides with the equation of the temporal evolution of the dynamic quantity $\delta D_{i j}(t)$, an equation for $g_{i j k l}(t)$ can be written in the form

[^0]\[

$$
\begin{equation*}
\frac{d}{d t} g_{i j k l}(t)=-\sum_{\alpha=1}^{3} \tau_{\alpha}^{-1} B_{i j m n}^{\alpha} g_{m n k l}(t) . \tag{4}
\end{equation*}
$$

\]

The structure of the tensor $g_{i j k l}(t)$, because of the uniaxial symmetry of the medium and the fact that $D_{i i}=0$, is determined by the expression

$$
\begin{equation*}
g_{i j k l}(t)=\sum_{\alpha=1}^{3} g_{\alpha}(t) B_{i j k l}^{\alpha} \tag{5}
\end{equation*}
$$

The coefficients $g_{\alpha}(t)$ obey three independent equations. The unknown correlation function has the form

$$
\begin{equation*}
g_{i j k l}(t)=\sum_{\alpha=1}^{3} g_{\alpha}(0) \exp \left(-\frac{t}{\tau_{\alpha}}\right) B_{i j k l}^{\alpha} . \tag{6}
\end{equation*}
$$

The independent coefficients $g_{\alpha}(0)$ define the static correlation function

$$
\begin{equation*}
g_{i j k l}(0)=\frac{1}{V} \iint\left\langle\delta \hat{D}_{i j}(\mathbf{x}, 0) \delta \hat{D}_{k l}\left(\mathbf{x}^{\prime}, 0\right)\right\rangle d \mathbf{x} d \mathbf{x}^{\prime} \tag{7}
\end{equation*}
$$

represented by the expression

$$
\begin{equation*}
g_{i j k l}(0)=\sum_{\alpha=1}^{3} g_{\alpha}(0) B_{i j k l}^{\alpha} \tag{8}
\end{equation*}
$$

For the coefficients $g_{\alpha}(t)$ in [2], formulas in the form of average values of the cosines and sines of the angle $\theta$ between the axis of a fragment of a DNA molecule and director are derived.

The times of relaxation of the orientational order $\tau_{\alpha}$ are determined with the aid of the formulas

$$
\begin{equation*}
\tau_{\alpha}=\frac{g_{\alpha}(0)}{F_{\alpha}} \tag{9}
\end{equation*}
$$

where $F_{\alpha}$ are the independent coefficients of the tensor

$$
\begin{equation*}
F_{i j k l}=\sum_{\alpha=1}^{3} F_{\alpha} B_{i j k l}^{\alpha} \tag{10}
\end{equation*}
$$

The tensor considered can be represented in terms of integrals of the following form:

$$
F_{i j k l}=\frac{1}{V} \int d \mathbf{x} \int d \mathbf{x}^{\prime} \int_{0}^{t} d t \exp (-\varepsilon t)\left\langle\hat{I}_{i j}^{D}(\mathbf{x}, t) \hat{I}_{k l}^{D}\left(\mathbf{x}^{\prime}, 0\right)\right\rangle
$$

with $\hat{I}_{i j}^{D}(\mathbf{x}, t)$ being a source in the equation of motion for microscopic tensor order parameters $\hat{D}_{i j}(\mathbf{x}, t)$ [2].
Calculation of the tensor of the kinetic coefficients $F_{i j k l}$ is performed approximately with the aid of the Fok-ker-Planck equation for a single-particle function of the distribution of orientational variables [2]. The result of calculation can be presented in the form

$$
\begin{equation*}
F_{1}=\frac{9 n k T}{4 \xi}\left(1-\overline{\cos ^{4} \theta}\right), \quad F_{2}=\frac{27 n k T}{2 \xi}\left(\overline{\cos ^{2} \theta}-\overline{\cos ^{4} \theta}\right), \quad F_{3}=\frac{9 n k T}{2 \xi}\left(1-\overline{\cos ^{2} \theta}+\overline{4 \cos ^{4} \theta}\right) . \tag{11}
\end{equation*}
$$

According to the Einstein formula, the coefficient of rotational friction $\xi$ is expressed in terms of the coefficient of rotational diffusion:

$$
\begin{equation*}
D=\frac{k T}{\xi} \tag{12}
\end{equation*}
$$

On the other hand, the coefficient $D$ can be calculated from the hydrodynamic formula [3]

$$
\begin{equation*}
D=\frac{k T}{6 \eta \Omega \delta} \tag{13}
\end{equation*}
$$

If the ratio of the length of the molecule to its diameter $L_{\mathrm{p}} / d=100$, then $\delta=721$ [3], whereas at $L_{\mathrm{p}} / d=25$, $\delta=62.8$. For the DNA molecule, it is characteristic that $L_{\mathrm{p}} / d=25$, which corresponds to $L_{\mathrm{p}}=500 \AA$ (persistent length) and diameter $d=20 \AA$. We note that "hydrodynamic" formula (13) corresponds to the results of the statistical model [4]. Thus, the times of relaxation $\tau_{\alpha}$ have been determined on the basis of the statistical theory.

We recall [2] that $\tau_{1}$ is the time of relaxation of biaxial fluctuations, $\tau_{2}$ is the time of relaxation of longitudinal fluctuations of ordering, and $\tau_{3}$ is the time of relaxation of transverse uniaxial fluctuations. It is of importance that in transition to the homogeneous state (degenerate as concerns the orientation of the director) of a nematic liquid crystal the quantity $\tau_{3}$ goes to infinity, and then the components of the ordering parameter $D_{23}$ and $D_{13}$ describe the so-called Goldstone hydrodynamic modes. If the degeneracy considered is removed by external fields or by the action of boundary conditions that create orientating forces, then $\tau_{3}$ is finite.

The formulas for $\tau_{\alpha}$ can be presenred in the form [2]

$$
\begin{equation*}
\tau_{1}=\tau \frac{7-10 \bar{P}_{2}+3 \bar{P}_{4}}{7-5 \bar{P}_{2}-2 \bar{P}_{4}}, \quad \tau_{2}=\tau \frac{7+10 \bar{P}_{2}+18 \bar{P}_{4}-35 \bar{P}_{2}}{7+5 \bar{P}_{2}-12 \bar{P}_{4}}, \quad \tau_{3}=\tau \frac{7+5 \bar{P}_{2}-12 \bar{P}_{4}}{14+5 \bar{P}_{2}+16 \bar{P}_{4}} \tag{14}
\end{equation*}
$$

Here $\tau=(6 D)^{-1}$, whereas $\bar{P}_{2}$ and $\bar{P}_{4}$ are average values of the Legendre polynomials expressed in terms of $\cos \theta$ :

$$
\begin{equation*}
\overline{\cos ^{2} \theta}=\frac{1}{3}\left(1+2 \bar{P}_{2}\right), \overline{\cos ^{4} \theta}=\frac{1}{35}\left(7+20 \bar{P}_{2}+8 \bar{P}_{4}\right) \tag{15}
\end{equation*}
$$

For subsequent calculations, the average values of $\overline{\cos ^{2} \theta}$ and $\overline{\cos ^{4} \theta}$ will be determined in the approximation of the molecular field from the formulas

$$
\begin{equation*}
\overline{\cos ^{2} \theta}=\frac{1}{3}(2 s+1), \overline{\cos ^{4} \theta}=\frac{1}{3}(2 s+1)-\frac{2}{3 b} \tag{16}
\end{equation*}
$$

Determination of the Viscosity Coefficients for the Ordered Phases of DNA Molecules. For statistical-mechanical description of the viscous properties of condensed systems in terms of the contemporary statistical nonequilibrium theory [5] it is necessary to use an equation for the microscopic tensor of stresses $\hat{\tau}_{i j}(\mathbf{x})$. An expression for this tensor was established earlier $[1,6]$ and it has the form

$$
\begin{equation*}
\hat{\tau}_{i j}(\mathbf{x})=-\sum_{v=1}^{N}\left(\frac{1}{m} p_{i}^{v} p_{j}^{v}+\frac{1}{2} \sum_{\mu \neq v}^{N} F_{i}^{v \mu} X_{j}^{v \mu}\right) \delta\left(\mathbf{x}-\mathbf{x}^{v}\right) \tag{17}
\end{equation*}
$$

The specificity of concentrated solutions containing rod-like macromolecules leads to the necessity of introducing a simplified relation for the microscopic tensor of stresses. Such equations that take into account the orientational degrees of freedom were suggested in [6-8]. In what follows, we will use the following expression:

$$
\begin{equation*}
\hat{\tau}_{i j}=3 k T \frac{p^{2}-1}{p^{2}+1}\left(c_{i} c_{j}-\frac{1}{3} \delta_{i j}\right)+\left(\frac{p^{2}}{p^{2}+1} c_{i} \frac{\partial U}{\partial c_{j}}-\frac{1}{p^{2}+1} c_{j} \frac{\partial U}{\partial c_{i}}\right) \tag{18}
\end{equation*}
$$

The single-particle microscopic tensor of stresses $\hat{\tau}_{i j}(\mathbf{x})$ will be represented as a sum of symmetrical and antisymmetrical parts:

$$
\begin{equation*}
\hat{\tau}_{i j}(\mathbf{x})=\hat{\tau}_{i j}^{\mathrm{s}}(\mathbf{x})+\hat{\tau}_{i j}^{\mathrm{a}}(\mathbf{x}) \tag{19}
\end{equation*}
$$

with

$$
\begin{gather*}
\hat{\tau}_{i j}^{\mathrm{s}}=3 k T \chi\left(c_{i} c_{j}-\frac{1}{3} \delta_{i j}\right)+\frac{1}{2} \chi\left(c_{i} \frac{\partial U}{\partial c_{j}}+c_{j} \frac{\partial U}{\partial c_{i}}\right),  \tag{20}\\
\hat{\tau}_{i j}^{\mathrm{a}}=\frac{1}{2}\left(c_{i} \frac{\partial U}{\partial c_{j}}-c_{j} \frac{\partial U}{\partial c_{i}}\right), \tag{21}
\end{gather*}
$$

where $\chi=\left(p^{2}-1\right) /\left(p^{2}+1\right)$ is the quantity characterizing the degree of elongation of a molecule (of a fragment of a DNA molecule). As the potential $U$ we will use its expression in the approximation of the molecular field:

$$
\begin{equation*}
U=-\frac{3}{2} k T b s \cos ^{2} \theta \tag{22}
\end{equation*}
$$

Having calculated the derivatives of potential (22), we will write down the relationship

$$
\begin{equation*}
c_{i} \frac{\partial U}{\partial c_{j}}+c_{j} \frac{\partial U}{\partial c_{i}}=-3 k \operatorname{Tbs}\left(c_{i} c_{l} n_{j} n_{l}+c_{j} c_{l} n_{i} n_{l}\right) \tag{23}
\end{equation*}
$$

Resorting to the formula below for the single-particle tensor order parameter:

$$
\begin{equation*}
\hat{d}_{i j}=\frac{1}{2}\left(3 c_{i} c_{j}-\delta_{i j}\right) \tag{24}
\end{equation*}
$$

we will represent (23) in the form

$$
\begin{equation*}
c_{i} \frac{\partial U}{\partial c_{j}}+c_{j} \frac{\partial U}{\partial c_{i}}=-2 k T b s\left(\hat{d}_{i l} n_{l} n_{j}+\hat{d}_{j l} n_{i} n_{l}+n_{i} n_{j}\right) \tag{25}
\end{equation*}
$$

The derivatives that determine the antisymmetric part of the tensor of stresses (21) are calculated in a similar way. As a result, we obtain the relationship

$$
\begin{equation*}
c_{i} \frac{\partial U}{\partial c_{j}}-c_{j} \frac{\partial U}{\partial c_{i}}=-2 k \operatorname{Tbs}\left(\hat{d}_{i l} n_{l} n_{j}-\hat{d}_{j l} n_{i} n_{l}\right) \tag{26}
\end{equation*}
$$

Based on Eqs. (25) and (26), we determine the dynamic value of the total tensor of stresses as the sum of its symmetrical and antisymmetrical parts:

$$
\begin{gather*}
\hat{\tau}_{i j}=2 k T \chi \sum_{\mathrm{v}=1}^{N} \hat{d}_{i j}^{v} \delta\left(\mathbf{x}-\mathbf{x}^{\mathrm{v}}\right)+k T b s \chi\left[\sum_{\mathrm{v}=1}^{N} \hat{d}_{i l}^{v} \delta\left(\mathbf{x}-\mathbf{x}^{v}\right) n_{l} n_{j}+\sum_{\mathrm{v}=1}^{N} \hat{d}_{j l}^{v} \delta\left(\mathbf{x}-\mathbf{x}^{v}\right) n_{i} n_{l}\right]+ \\
+k T b s\left[\sum_{\mathrm{v}=1}^{N} \hat{d}_{i l}^{\mathrm{v}} \delta\left(\mathbf{x}-\mathbf{x}^{\mathrm{v}}\right) n_{j} n_{l}-\sum_{\mathrm{v}=1}^{N} \hat{d}_{j l}^{\mathrm{v}} \delta\left(\mathbf{x}-\mathbf{x}^{\mathrm{v}}\right) n_{i} n_{l}\right] . \tag{27}
\end{gather*}
$$

In deriving Eq. (27), summation was made over the number of particles, with each term being multiplied by $\delta(\mathbf{x}$ $-\mathbf{x}^{v}$ ).

Using the expression for the density of the dynamic value of the tensor order parameter:

$$
\begin{equation*}
\hat{D}_{i j}(\mathbf{x})=\sum_{v=1}^{N} d_{i j}^{v} \delta\left(\mathbf{x}-\mathbf{x}^{v}\right)=\sum_{v=1}^{N} \frac{1}{2}\left(3 c_{i}^{v} c_{j}^{v}-\delta_{i j}\right) \delta\left(\mathbf{x}-\mathbf{x}^{v}\right), \tag{28}
\end{equation*}
$$

we write down the density of the dynamic value of the microscopic tensor of stresses in the form

$$
\begin{equation*}
\hat{\tau}_{i j}(\mathbf{x})=2 k T \chi \hat{D}_{i j}(\mathbf{x})-k T \chi b s\left(\hat{D}_{i l} n_{l} n_{j}+\hat{D}_{j l} n_{i} n_{l}\right)-k T b s\left(\hat{D}_{i l} n_{l} n_{j}-\hat{D}_{j l} n_{i} n_{l}\right) \tag{29}
\end{equation*}
$$

or

$$
\begin{equation*}
\hat{\tau}_{i j}(\mathbf{x})=2 k T \chi \hat{D}_{i j}-k T b s(\chi+1) n_{j} n_{l} \hat{D}_{l i}-k T b s(\chi-1) n_{i} n_{l} \hat{D}_{l j} \tag{30}
\end{equation*}
$$

As a result of nonequilibrium averaging (30), the value of the tensor of stresses is determined in terms of the density of the tensor order parameters:

$$
\begin{equation*}
\tau_{i j}=2 k T D_{i j}-k T b s(\chi+1) n_{j} n_{l} D_{l i}-k T b s(\chi-1) n_{i} n_{l} D_{l j} . \tag{31}
\end{equation*}
$$

However, the nonequilibrium average value of $D_{i j}$ consists of the sum of the equilibrium value $D_{i j}^{0}$ and nonequilibrium addition:

$$
\begin{equation*}
D_{i j}=D_{i j}^{0}+K_{i j k l} \beta \dot{\varepsilon}_{k l} \tag{32}
\end{equation*}
$$

where

$$
\begin{equation*}
\dot{\varepsilon}_{k l}=\frac{\partial \vartheta_{k}}{\partial x_{l}}-e_{m l k} \omega_{m} \tag{33}
\end{equation*}
$$

The equilibrium value of the tensor order parameter

$$
\begin{equation*}
D_{i j}^{0}=\frac{1}{2} \operatorname{sn}\left(3 n_{i} n_{j}-\delta_{i j}\right) \tag{34}
\end{equation*}
$$

determines the equilibrium portion of the tensor of stresses $\tau_{i j}^{0}$. At the same time, the nonequilibrium addition $K_{i j k l} \beta \dot{\varepsilon}_{k l}$ in the quantity $D_{i j}$ is proportional to the deformation-rate tensor. On substitution of this addition into expression (31), we establish a linear relationship between the nonlinear tensor of stresses and the tensor of deformation rates. The proportionality factors in the relation indicated form a tensor of the viscosity coefficients of the media studied.

The constitutive equation for the tensor of viscous stresses is written in the form

$$
\begin{equation*}
\tau_{i j}-\tau_{i j}^{0}=\left[\left(\chi \delta_{i j}-b s(\chi+1) n_{j} n_{l}\right) K_{l i m n}+\left(\chi \delta_{i j}-b s(\chi-1) n_{i} n_{l}\right) K_{l j m n}\right] \dot{\varepsilon}_{m n} \tag{35}
\end{equation*}
$$

We will denote the tensor of the viscosity coefficients by $a_{i j k l}$; then

$$
\begin{equation*}
a_{i j k l}=2 \chi K_{i j k l}-b s(\chi+1) n_{j} n_{m} K_{m i k l}-b s(\chi-1) n_{i} n_{m} K_{m j k l} . \tag{36}
\end{equation*}
$$

In this approach, computation of the viscosity coefficients is reduced to calculation of the tensor $K_{i j k l}$, which, according to (32), determines the nonequilibrium contribution to the tensor order parameter. Relation (32) results from averaging of the tensor parameter with the aid of the nonequilibrium distribution function [2, 5]:

$$
\begin{equation*}
f=f_{0}+\Sigma \int d \mathbf{x}^{\prime} \int_{-\infty}^{0} d t^{\prime} \exp \left[\left(\varepsilon+\left(1-P_{\mathrm{M}}\right) i \hat{L}\right) t^{\prime}\right] f_{0} \hat{j}^{m}\left(\mathbf{x}^{\prime}\right) X_{m}\left(\mathbf{x}^{\prime}, t+t^{\prime}\right) \tag{37}
\end{equation*}
$$

Among the dynamic values of irreversible flows $\hat{j}^{m}$ there is a microscopic tensor of stresses, i.e.,

$$
\begin{equation*}
\hat{j}^{m}=\left(1-P_{\mathrm{M}}\right) \hat{\tau}_{i j} . \tag{38}
\end{equation*}
$$

In (37), the conjugated thermodynamic force $X_{m}$ is equal to $\beta \dot{\varepsilon}_{i k}$. We note that $f_{0}$ is the equilibrium function of distribution and $P_{\mathrm{M}}$ is the Mori projection operator. In what follows, for the homogeneous case considered, the Liouville operator $\left(1-P_{\mathrm{M}}\right) \hat{L}$ is reduced to a conventional operator $\hat{L}$, with the parameter $\varepsilon \rightarrow 0$ after the thermodynamic limiting transition.

An expression for the tensor $K_{i j k l}$ is derived by performing the above-mentioned nonequilibrium averaging $\hat{D}_{i j}$ with the aid of the distribution function (37):

$$
\begin{equation*}
K_{i j k l}=\int d \mathbf{x}^{\prime} \int_{0}^{\infty} \exp (\varepsilon \tau)\left\langle\hat{D}_{i j}\left(\mathbf{x}^{\prime}, \tau\right) \hat{\tau}_{k l}(0)\right\rangle d \tau . \tag{39}
\end{equation*}
$$

However, according to (30), the microscopic tensor of stresses is expressed in terms of the dynamic value of the tensor order parameter. Ultimately, computation of the tensor $K_{i j k l}$ is reduced to calculation of integrals of the time correlation function of the tensor order parameter:

$$
\begin{align*}
& K_{i j k l}=\left[\int d \mathbf{x}^{\prime} \int_{0}^{\infty} \exp (\varepsilon \tau)\left\langle\hat{D}_{i j}(\tau) \hat{D}_{m k}\right\rangle d \tau\right] k T\left(\chi \delta_{l m}-b s(\chi+1) n_{l} n_{m}\right)+ \\
& \quad+\left[\int d \mathbf{x}^{\prime} \int_{0}^{\infty} \exp (\varepsilon \tau)\left\langle\hat{D}_{i j}(\tau) \hat{D}_{m l}\right\rangle d \tau\right] k T\left(\chi \delta_{k m}-b s(\chi-1) n_{k} n_{m}\right) . \tag{40}
\end{align*}
$$

Calculation of the integrals considered is made on the basis of the explicit relation for the above-established time correlation function:

$$
\begin{equation*}
g_{i j k l}(t)=\sum_{\alpha=1}^{3} g_{\alpha}(t) B_{i j k l}^{\alpha}, \quad g_{\alpha}(t)=g_{\alpha}(0) \exp \left(-\frac{t}{\tau_{\alpha}}\right) \tag{41}
\end{equation*}
$$

As a result, the tensor $K_{i j k l}$ can be represented in the form

$$
\begin{equation*}
K_{i j k l}=k T\left(\chi \delta_{l m}-b s(\chi+1) n_{l} n_{m}\right) \Sigma g_{\alpha}(0) \tau_{\alpha} B_{i j m k}^{\alpha}+k T\left(\chi \delta_{k m}-b s(\chi-1) n_{k} n_{m}\right) \Sigma g_{\alpha}(0) \tau_{\alpha} B_{i j m l}^{\alpha} . \tag{42}
\end{equation*}
$$

To simplify the representation, in what follows we introduce the notation

$$
\begin{equation*}
b_{\alpha}=g_{\alpha}(0) \tau_{\alpha} . \tag{43}
\end{equation*}
$$

Substituting the tensor $K_{i j k l}$ (42) into the expression for the viscosity coefficients (36), we obtain the following formula:

$$
\begin{align*}
& \frac{a_{i j k l}}{k T}= 4 \chi^{2} \Sigma b_{\alpha} B_{i j k l}^{\alpha}-2 b s \chi(\chi+1)\left(n_{l} n_{m} \Sigma b_{\alpha} B_{i j k l}^{\alpha}+n_{n} n_{j} \Sigma b_{\alpha} B_{i j k l}^{\alpha}\right)-2 b s \chi(\chi-1) \times \\
& \times\left(n_{k} n_{m} \Sigma b_{\alpha} B_{i j m l}^{\alpha}+n_{i} n_{n} \Sigma b_{\alpha} B_{n j k l}^{\alpha}\right)+b s^{2}\left(\chi^{2}-1\right)\left(n_{j} n_{m} n_{n} n_{k} \Sigma b_{\alpha} B_{i m n l}^{\alpha}++n_{i} n_{n} n_{l} n_{m} \Sigma b_{\alpha} B_{n j m k}^{\alpha}\right)+ \\
&+b s^{2}(\chi+1)^{2} n_{j} n_{l} n_{m} n_{n} \Sigma b_{\alpha} B_{i m k n}^{\alpha}+b s^{2}(\chi-1)^{2} n_{i} n_{n} n_{l} n_{m} \Sigma b_{\alpha} B_{n j m l}^{\alpha} . \tag{44}
\end{align*}
$$

Using the explicit form of the Stratanovich matrices, we can represent the tensor $\sum b_{\alpha} \beta_{i j k l}^{\alpha}$ in (44) in the form

$$
\begin{gathered}
\Sigma b_{\alpha} B_{i j k l}^{\alpha}=b_{1} B_{i j k l}^{(1)}+b_{2} B_{i j k l}^{(2)}+b_{3} B_{i j k l}^{(3)}=\left(\frac{b_{2}}{6}-\frac{b_{1}}{2}\right) \delta_{i j} \delta_{k l}+\frac{b_{1}}{2}\left(\delta_{i k} \delta_{j l}+\delta_{i l} \delta_{j k}\right)+ \\
+\left(\frac{b_{1}}{2}-\frac{b_{2}}{2}\right)\left(\delta_{i j} n_{k} n_{l}+\delta_{k l} n_{i} n_{j}\right)+\left(\frac{b_{3}}{2}-\frac{b_{1}}{2}\right)\left(\delta_{i l} n_{j} n_{k}+\delta_{i k} n_{j} n_{l}+\delta_{j l} n_{i} n_{k}+\delta_{j k} n_{i} n_{l}\right)+\left(\frac{b_{1}}{2}+\frac{3 b_{2}}{2}-2 b_{3}\right) n_{i} n_{j} n_{k} n_{l}
\end{gathered}
$$

Then the explicit expression for the tensor of the viscosity coefficients can be written as

$$
\begin{gather*}
\frac{a_{i j k l}}{k T}=2 \chi^{2}\left(\frac{b_{2}}{3}-b_{1}\right) \delta_{i j} \delta_{k l}+2 \chi^{2} b_{1} \delta_{i k} \delta_{j l}+2 \chi^{2} b_{1} \delta_{i l} \delta_{j k}+2 \chi^{2}\left(b_{1}-b_{2}\left(1-\frac{2 b s}{3}\right)\right)\left(\delta_{i j} n_{l} n_{k}+\delta_{k l} n_{i} n_{j}\right)+ \\
+2\left(\chi^{2}\left(b_{3}-b_{1}\right)+\left(\frac{b s^{2}}{4}(\chi+1)^{2}-b s \chi(\chi+1)\right) b_{3}\right) \delta_{i k} n_{j} n_{l}+2\left(\chi^{2}\left(b_{3}-b_{1}\right)+\left(b s^{2}\left(\chi^{2}-1\right)-b s \chi^{2}\right) b_{3}\right) \times \\
\times\left(\delta_{i l} n_{j} n_{k}+\delta_{j k} n_{i} n_{l}\right)+2\left(\chi^{2}\left(b_{3}-b_{1}\right)+\left(\frac{b s^{2}}{4}(\chi-1)^{2}-b s \chi(\chi-1)\right) b_{3} \times\right. \\
\times \delta_{j l} n_{i} n_{k}+2 \chi^{2}\left(\left(b_{1}+3 b_{2}-4 b_{3}\right)+b s^{2}\left(\frac{4 b_{2}}{3}-b_{3}\right)-4 b s\left(b_{2}-b_{3}\right)\right) n_{i} n_{j} n_{k} n_{l} \tag{45}
\end{gather*}
$$

We will take into consideration that for a uniaxial centrosymmetrical medium the tensor $a_{i j k l}$ has the following structure [2]:

$$
\begin{align*}
& a_{i j k l}=a_{1} \delta_{i j} \delta_{k l}+a_{2} \delta_{i k} \delta_{j l}+a_{3} \delta_{j l} \delta_{j k}+a_{4}\left(\delta_{i j} n_{k} n_{l}+\delta_{k l} n_{i} n_{j}\right)+ \\
& +a_{5} \delta_{i k} n_{j} n_{l}+a_{6}\left(\delta_{j l} n_{j} n_{k}+\delta_{j k} n_{i} n_{l}\right)+a_{7} \delta_{j l} n_{i} n_{k}+a_{8} n_{i} n_{j} n_{k} n_{l} \tag{46}
\end{align*}
$$

On the basis of relation (45) we derive formulas for the viscosity coefficients:

$$
\begin{gather*}
a_{1}=2 k T \chi^{2}\left(\frac{b_{2}}{3}-b_{1}\right), a_{2}=a_{3}=2 k T \chi^{2} b_{1}, a_{4}=2 k T \chi^{2}\left(b_{1}-b_{2}\left(1-\frac{2 b s}{3}\right)\right), \\
a_{5}=2 k T\left(\chi^{2}\left(b_{3}-b_{1}\right)+\left(\frac{b s^{2}}{4}(\chi+1)^{2}-b s \chi(\chi+1)\right) b_{3}\right), a_{6}=2 k T\left(\chi^{2}\left(b_{3}-b_{1}\right)+\left(b s^{2}\left(\chi^{2}-1\right)-b s \chi^{2}\right) b_{3}\right), \\
a_{7}=2 k T\left(\chi^{2}\left(b_{3}-b_{1}\right)+\left(\frac{b s^{2}}{4}(\chi-1)^{2}-b s \chi(\chi-1)\right) b_{3}\right), \\
a_{8}=2 \chi^{2}\left(\left(b_{1}+3 b_{2}-4 b_{3}\right)+b s^{2}\left(\frac{4 b_{2}}{3}-b_{3}\right)-4 b s\left(b_{2}-b_{3}\right)\right) \tag{47}
\end{gather*}
$$

In view of the lack of any data on the viscosity and kinetic parameters of the systems investigated, there is a pressing need to determine the indicated quantities on the basis of the theory developed.

To estimate the coefficients of rotational diffusion, we will use hydrodynamic formula (13). The volume of a fragment of the molecule $\Omega=\pi r^{2} L_{\mathrm{p}}$ is calculated from the persistent length and $L_{\mathrm{p}}=500 \AA$ and the cross-section radius $r=10 \AA$. As a result, we obtain $\Omega=1.571 \cdot 10^{-25} \mathrm{~m}^{3}$. Since the form-factor is equal to 62.8 and water viscosity is $\eta=10^{-3} \mathrm{~Pa} \cdot \mathrm{sec}$, then at $T=300 \mathrm{~K}$ and $D=1.099 \cdot 10^{5} \mathrm{sec}^{-1}$. The relaxation times are calculated from formulas (14), where the average values of the Legendre polynomials are determined with the aid of formulas (15) and (16). Then

$$
\tau_{1}=\frac{1-s-\frac{1}{b}}{4 D\left(1-s+\frac{1}{b}\right)}, \quad \tau_{2}=\frac{\left(1+s-2 s^{2}-\frac{3}{b}\right) b}{12 D}, \tau_{3}=\frac{1}{2 b D\left(2+s-\frac{4}{b}\right)}
$$

At $s=0.5$, we obtain that $\tau_{1}=0.865 \cdot 10^{-6} \mathrm{sec}, \tau_{2}=1.169 \cdot 10^{-6} \mathrm{sec}$, and $\tau_{3}=0.619 \cdot 10^{-6} \mathrm{sec}$. Single-particle expressions for $g_{\alpha}$ are written on the basis of [2] in the form

$$
g_{1}=\frac{9}{16} n \sin ^{4} \theta, \quad g_{2}=\frac{27}{8} n\left(\overline{\cos ^{4} \theta}-\overline{\cos ^{2} \theta}\right), \quad g_{3}=\frac{9}{4} n\left(\overline{\cos ^{2} \theta}-\overline{\cos ^{4} \theta}\right)
$$

or subject to (16) for $\overline{\cos ^{2} \theta}$ and $\overline{\cos ^{4} \theta}$ in the form

$$
g_{1}=\frac{3 n}{8}\left(1-s-\frac{1}{b}\right), \quad g_{2}=\frac{3 n}{4}\left(1+s-2 s^{2}-\frac{3}{b}\right), \quad g_{3}=\frac{3 n}{2 b} .
$$

For numerical estimations we assume that $b=4.5415$ and $s=0.5$. The density of the number of DNA molecule fragments will be calculated from the formula $n=\rho / m$. Here $m$ is the mass of a fragment of the molecule and $\rho=(10-300) \mathrm{kg} / \mathrm{m}^{3}$ is its mass density. At the same time, the mass of the molecule fragment, the length of which is equal to the persistent one, is determined as $m=147 m_{\mathrm{b}}$, where $m_{\mathrm{b}}$ is the mass of a pair of nitrogen bases, and 147 is their number layed out on the persistent length. Since $m_{\mathrm{b}}=\left(615 \cdot 10^{-3}\right) /\left(6.02 \cdot 10^{23}\right)=1.02 \cdot 10^{-24} \mathrm{~kg}(615 \mathrm{~g}$ is the molecular mass, $6.02 \cdot 10^{23}$ is the Avogadro number), as a result $m=1.5 \cdot 10^{-22} \mathrm{~kg}$.

In what follows, the estimation will be made at $n=150 /\left(1.5 \cdot 10^{-22}\right)=10^{24} \mathrm{~m}^{-3}$ assuming that $\rho=150$ $\mathrm{kg} / \mathrm{m}^{3}$. As a result, we obtain that $g_{1}=0.1033 \cdot 10^{24} \mathrm{~m}^{-3}, g_{2}=0.2546 \cdot 10^{24} \mathrm{~m}^{-3}$, and $g_{3}=0.3303 \cdot 10^{24} \mathrm{~m}^{-3}$ and the parameters $b_{\alpha}$ from (43) are equal to $b_{1}=0.8936 \cdot 10^{17}, b_{2}=0.3479 \cdot 10^{18}$, and $b_{3}=0.2044 \cdot 10^{18}$. For the ordered phase ${ }_{\circ}$ of DNA molecules, fragments of length of the order of the persistent one $L_{\mathrm{p}} \approx 500 \AA$ with cross-sectional diameter 20 $\AA$ are considered; therefore $p=25$ and $\chi$ can be assumed equal to unity. For these data at $k T=4.14 \cdot 10^{-21}(T=300$ K) the viscosity coefficients can be estimated from expressions (47):

$$
\begin{gathered}
a_{1}=2.203 \cdot 10^{-4} \mathrm{~Pa} \cdot \mathrm{sec}, a_{2}=a_{3}=7.399 \cdot 10^{-4} \mathrm{~Pa} \cdot \mathrm{sec}, a_{4}=22.200 \cdot 10^{-4} \mathrm{~Pa} \cdot \mathrm{sec} \\
a_{5}=19.930 \cdot 10^{-4} \mathrm{~Pa} \cdot \mathrm{sec}, a_{6}=-28.910 \cdot 10^{-4} \mathrm{~Pa} \cdot \mathrm{sec}, a_{7}=9.525 \cdot 10^{-4} \mathrm{~Pa} \cdot \mathrm{sec}, a_{8}=28.97 \cdot 10^{-4} \mathrm{~Pa} \cdot \mathrm{sec}
\end{gathered}
$$

The viscosity coefficients $a_{i}$ allow one to calculate the so-called Leslie coefficients:

$$
\begin{gathered}
\alpha_{1}=a_{8}, \quad \alpha_{2}=a_{6}-a_{5}, \quad \alpha_{3}=a_{7}-a_{6}, \quad \alpha_{4}=a_{2}+a_{3} \\
\alpha_{5}=a_{5}+a_{6}, \quad \alpha_{6}=a_{6}+a_{7}, \quad \gamma_{1}=\alpha_{3}-\alpha_{2}, \quad \gamma_{2}=\alpha_{2}+\alpha_{3}
\end{gathered}
$$

In order of magnitude, the viscosity coefficients are close to the shear-viscosity coefficient of water, which is a solvent containing fragments of a DNA molecule. The negative value of $a_{6}$ is due to the approximate character of expressions for the microscopic tensor of stresses and correlator of the tensor order parameter. It is essential that viscosity be an anisotropic characteristic of the medium.

## NOTATION

$B_{i j k l}^{\alpha}(\alpha=1,2,3)$, Stratanovich matrices (see, e.g., [2]); $b$, quantity characterizing the intensity of interaction of a selected molecule with its surroundings; $\mathbf{c}_{i}^{v}$, projection of a unit vector $\mathbf{c}^{\vee}$ directed along the axis of the DNA molecule fragment numbered $v$ onto the $x_{i}$ axis; $D$, coefficient of rotational diffusion; $e_{m l k}$, Levi-Civita tensor; $F_{i}^{v \mu}$, $i$ th projection of the force of interaction of two particles numbered $v$ and $\mu ; k$, Boltzmann constant; $N$, number of molecule fragments in the system; $n=N / V$, density of the number of fragments; $n_{i}$, director; $p=L_{\mathrm{p}} / d$, ratio of the molecule length $L_{\mathrm{p}}$ to its diameter $d ; p_{i}^{v}$, projection of the pulse of a particle numbered $v$ onto the $x_{i}$ axis; s, scalar
ordering parameter of ordering; $T$, absolute temperature; $t$, time; $U$, single-particle potential energy of a molecule; $V$, volume of the system; $X_{j}^{\gamma \mu}$, projection of the vector that connects the centers of mass of two particles on the $x_{j}$ axis; $\mathbf{x}^{\nu}$, radius-vector of the center of mass of the fragment of the DNA molecule numbered $v ; \beta=(k T)^{-1}$; $\delta$. form-factor, dimensionless quantity, depending on the ratio of $L_{\mathrm{p}}$ to $d ; \delta\left(\mathbf{x}-\mathbf{x}^{v}\right)$, Dirac delta function; $\delta_{i j}$, Kronecker symbol; $\dot{\varepsilon}_{k l}$, tensor of deformation rates; $\eta$, viscosity of the medium; $\xi$, coefficient of rotational friction; $\tau_{\alpha}$, relaxation time; $\vartheta_{k}$, flow velocity of the medium; $\Omega$, volume of the DNA molecule fragment the length of which is equal to its persistent length; $\omega_{m}$, mean angular velocity of the proper rotation of the medium molecules. Subscripts: a, antisymmetric part; b, bases; p, persistent; s, symmetrical part; ${ }^{\wedge}$, microscopic value. Superscripts: over bar, average value; ', variables with respect to which integration is made.

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